



# **Evaluating and Modeling Social Intelligence: A Comparative Study of Human and AI Capabilities**

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**Motivation**

- **Evaluating AI Social Intelligence:** Investigate whether large language models can match human-level social intelligence, a key differentiator of human cognition.
- **Benchmarking AI Performance:** Provide a systematic framework to evaluate and compare the social capabilities of AI systems against human performance.
- Advancing AGI Development: Identify the current limitations of AI in social intelligence to guide future research and development toward achieving Artificial General Intelligence (AGI).

- Novel Assessment Framework: Introduce a comprehensive benchmark for evaluating social intelligence through tasks like Inverse Reasoning (IR) and Inverse Inverse Planning (IIP), assessing critical cognitive dimensions.
- Recursivef Bayesian Inference Model: Present a computational model capable of interpreting social interactions and capturing the nuances of human social reasoning through recursive Bayesian inference.
- **Empirical Insights:** Provide a detailed analysis comparing human participants, state-of-the-art language models, and the proposed computational model, highlighting the significant gap between AI and human social cognition.



Two basic tasks, Inverse Reasoning (IR) and Inverse Inverse Planning (IIP), are desined to evaluate social intelligence. IR tasks requires to infer actor's *preference* on targets from observation, IIP asks to plan a path with considering observer's inference of actor's *destination*.

# **Contribution**

Input: Agents *i, j*, likelihood *M*, priors  $\mathbb{P}_p(\gamma)$ ,  $\mathbb{P}_p(h)$ . Output: Posteriors  $\mathbb{P}_p(\gamma), \mathbb{P}^1(h|\gamma), \mathbb{P}^2$  $(\gamma|h), \ldots$ ).

1 Initialize:  $\mathbb{P}^0_i$  $\frac{0}{i}(\gamma|h)$   $\propto$  *M*( $\gamma$ , *h*),  $k = 0$ . 2 for  $k = 0$  to  $\infty$  do

 $\mathbb{P}^{2k+1}(h|\gamma) := \mathbb{P}^{2k}(\gamma|h)\mathbb{P}_p(h)/\mathbb{P}(\gamma)$  $\mathbb{P}^{2k+2}(\gamma|h) := \mathbb{P}^{2k+1}(h|\gamma)\mathbb{P}_p(\gamma)/\mathbb{P}(h)$ <sup>5</sup> end

5 end<br>6 return  $(\mathbb{P}_p(\gamma), \mathbb{P}^1(h|\gamma), \mathbb{P}^2)$  $(\gamma|h), ...$ ).

- $h \in H$ : hypothesis, *preference* in IR, and *destination* in IIP.
- $\gamma \in \Gamma$ : a finite path set on the 5 by 5 grid.
- *M*: likelihood. Describing a "natural" statistical relation between *γ* and *h*.
- $\blacksquare$  In our tasks,  $M$  is set to be

## **Evaluation Tasks**

 $M(\gamma, h)$   $\propto$   $\sum_{k=1}^{|\gamma|-1}$  $\frac{1}{k+1} \varphi(\gamma_{[0:k+1]}, h)e^{-\beta k}, \quad (1)$ where  $\alpha$ ,  $\beta$ ,  $\varphi$  are numerical and functional parameters.

**P**<sub>p</sub> $(\gamma)$ ,  $\mathbb{P}_p(h)$ , priors on paths / hypotheses.



Figure 2. A realistic-style figure showing IR and IIP tasks.





(d) IIP Rte A (e) IIP Rte B (f) IIP Rte C (g) IIP Rte D *Shortest Avoidant Reversed Hybrid*

<span id="page-0-0"></span>Figure 3. Input stimuli examples for both tasks.





#### Figure 4. (a-c) IR task types. (d-g) IIP task types with *Hybrid* routes.

# **Computational Model**

A general model for ToM is constructed using recursive Bayesian inference. Specific likelihood and priors are constructed for the two tasks.

Algorithm 1: Iterative Bayesian Inference

Figure 6. Accuracy on the IR Task. In (a) and (b), "Favorite" assesses accuracy for the top preference only, "Visible" for the preference order among  $\{X, Y, Z, M\}$ , and "Strict" for the entire preference order. In (b) and (d), we uniformly use a Previsited type case as the one-shot learning example. In (c) and (d), accuracies are evaluated solely based on the "Strict" criterion.

#### Result of Experiments on IIP

Figure 7. Distribution of Options in IIP. The numerical values at top of each bar represent the respective test counts. In (b) and (d), we uniformly use a Type III case as the one-shot learning example.

#### E Bayesian Model Likelihood and Regression

### **Computational Model**

Based on the construction, varying two parameters results in various behaviors.



<span id="page-0-1"></span>Figure 5. Model predictions based on posterior probability over parameters  $e^{-\alpha}$  and  $e^{-\beta}$  on one example [\(3\(](#page-0-0)c-g)). The regions are designated according to the route types with the highest posterior. The color intensity within each region indicates the probability gap between the most likely and the second-most likely options, effectively visualizing the model's confidence in its predictions. Four figures are labeled by values of parameters  $(exp(-\theta), \delta)$ .

Figure 8. IIP modeling results. (a-b) Likelihood landscapes in the  $\alpha$ - $\beta$  dimension ( $e^{-\theta} = 0.99$ ,  $\delta = 100$ ), comparing "human average" with "GPT-4"; region boundaries and labels are calculated as in [5](#page-0-1) on the whole dataset. (c-d) Regression for human average, LLM and individual humans, mapped onto two planes respectively.

#### $\triangle$  Shortcut Analysis

Table 3. IIP shortcuts analysis. We use route type classification accuracy (%) as the metric.

### **Experiments**

- Subjects: GPT 3.5 Turbo, GPT 4 Turbo, GPT 4V, and 75 human subjects.
- **Experiment types:** 
	- **EXEX 2 Zero-shot** vs. one-shot for IR and IIP
	- **Text** vs. **image** for IR and IIP
	- **Bayesian model regression** for IIP
- **Shortcut analysis** for IR and IIP

#### **Let** Result of Experiments on IR









*Reversed Shortest Avoidant Hybrid* Avg

Overall 99.4 95.2 91.0 94.2 94.9

Table 2. IIP path type classification accuracy.



# **Conclusion**

We introduced a comprehensive benchmark for evaluating social intelligence, comprising a unified computational frame- work, representative tasks, and evaluation criteria. Our results demonstrate a marked superiority of humans over LLMs in social intelligence tasks. We hope that our study contributes valuable information towards the advancement of ASI.